

### Start-Up and Service Instructions

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#### SAFETY CONSIDERATIONS

Centrifugal and screw compressor liquid chillers are designed to provide safe and reliable service when operated within design specifications. When operating this equipment, use good judgment and safety precautions to avoid damage to equipment and property or injury to personnel.

Be sure you understand and follow the procedures and safety precautions contained in the chiller instructions as well as those listed in this guide.

### **⚠ DANGER**

Failure to follow these procedures will result in severe personal injury or death.

ONLY QUALIFIED electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment.

READ AND UNDERSTAND this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.

DO NOT install modification kits with power applied to the drive. Disconnect and lock out incoming power before attempting such installation or removal. Failure to observe this precaution could result in severe bodily injury or loss of life.

UNUSED WIRES in conduit must be grounded at both ends to avoid a possible shock hazard caused by induced voltages. Also, if a drive sharing a conduit is being serviced or installed, all drives using this conduit should be disabled to eliminate the possible shock hazard from cross-coupled motor leads. Failure to observe these precautions could result in bodily injury.

DO NOT VENT refrigerant relief valves within a building. Outlet from rupture disc or relief valve must be vented outdoors in accordance with the latest edition of ANSI/ASHRAE 15 (American National Standards Institute/American Society of Heating, Refrigerating, and Air-Conditioning Engineers). The accumulation of refrigerant in an enclosed space can displace oxygen and cause asphyxiation.

PROVIDE adequate ventilation in accordance with ANSI/ASHRAE 15, especially for enclosed and low overhead spaces. Inhalation of high concentrations of vapor is harmful and may cause heart irregularities, unconsciousness, or death. Misuse can be fatal. Vapor is heavier than air and reduces the amount of oxygen available for breathing. Product causes eye and skin irritation. Decomposition products are hazardous.

DO NOT USE OXYGEN to purge lines or to pressurize a chiller for any purpose. Oxygen gas reacts violently with oil, grease, and other common substances.

NEVER EXCEED specified test pressures. VERIFY the allowable test pressure by checking the instruction literature and the design pressures on the equipment nameplate.

DO NOT USE air for leak testing. Use only refrigerant or dry nitrogen.

DO NOT VALVE OFF any safety device.

BE SURE that all pressure relief devices are properly installed and functioning before operating any chiller.

THERE IS A RISK OF INJURY OR DEATH by electrocution. High voltage may be present on the motor leads even though the motor is not running. Open the power supply disconnect before touching motor leads or terminals.

### **MARNING**

Failure to follow these procedures may result in personal injury or death.

DO NOT USE TORCH to remove any component. System contains oil and refrigerant under pressure.

To remove a component, wear protective gloves and goggles and proceed as follows:

- a. Shut off electrical power to unit.
- b. Recover refrigerant to relieve all pressure from system using both high-pressure and low-pressure ports.
- c. Traces of vapor should be displaced with nitrogen and the work area should be well ventilated. Refrigerant in contact with an open flame produces toxic gases.
- d. Cut component connection tubing with tubing cutter and remove component from unit. Use a pan to catch any oil that may come out of the lines and as a gage for how much oil to add to the system.
- e. Carefully unsweat remaining tubing stubs when necessary. Oil can ignite when exposed to torch flame.

DO NOT work on high-voltage equipment unless you are a qualified electrician.

DO NOT WORK ON electrical components, including control panels, switches, VFD, or oil heater until you are sure ALL POWER IS OFF and no residual voltage can leak from capacitors or solid-state components.

LOCK OPEN AND TAG electrical circuits during servicing. IF WORK IS INTERRUPTED, confirm that all circuits are de-energized before resuming work.

AVOID SPILLING liquid refrigerant on skin or getting it into the eyes. USE SAFETY GOGGLES. Wash any spills from the skin with soap and water. If liquid refrigerant enters the eyes, IMMEDIATELY FLUSH EYES with water and consult a physician.

DO NOT ATTEMPT TO REMOVE fittings, covers, etc., while chiller is under pressure or while chiller is running. Be sure pressure is at 0 psig (0 kPa) before breaking any refrigerant connection.

### **ACAUTION**

Failure to follow these procedures may result in personal injury or damage to equipment.

TO AVOID an electric shock hazard, verify that the voltage on the bus capacitors has discharged completely before servicing. Check the DC bus voltage at the power terminal block by measuring between the +DC and -DC terminals, between the +DC terminal and the chassis, and between the -DC terminal and the chassis. The voltage must be zero for all 3 measurements.

THE USER is responsible to conform with all applicable local, national, and international codes. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

THIS DRIVE contains ESD (electrostatic discharge) sensitive parts and assemblies. Static control precautions are required when installing, testing, servicing or repairing this assembly. Component damage may result if ESD control procedures are not followed. For static control procedures, reference Rockwell publication Guarding Against Electrostatic Damage, or any other applicable ESD protection handbook.

DO NOT alter the setting of any jumper. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

USE OF power correction capacitors on the output of the drive can result in erratic operation of the motor, nuisance tripping, and/or permanent damage to the drive. Remove power correction capacitors before proceeding. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

MOST CODES require that upstream branch circuit protection be provided to protect input power wiring. If fuses are chosen as the protection method, refer to the PowerFlex 750 user manual. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

DO NOT route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

DISTRIBUTION SYSTEM short circuit capacity shall not exceed the rating of the drive. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

DO NOT STEP on refrigerant lines. Broken lines can whip about and release refrigerant, causing personal injury.

DO NOT climb over a chiller. Use platform, catwalk, or staging. Follow safe practices when using ladders.

USE MECHANICAL EQUIPMENT (crane, hoist, etc.) to lift or move inspection covers or other heavy components. Even if components are light, use mechanical equipment when there is a risk of slipping or losing your balance.

BE AWARE that certain automatic start arrangements CAN ENGAGE THE VFD, TOWER FAN, OR PUMPS. Open the disconnect ahead of the VFD, tower fans, or pumps.

USE only repair or replacement parts that meet the code requirements of the original equipment.

PERIODICALLY INSPECT all valves, fittings, and piping for corrosion, rust, leaks, or damage.

DO NOT re-use compressor oil or any oil that has been exposed to the atmosphere. Dispose of oil per local codes and regulations.

DO NOT leave refrigerant system open to air any longer than the actual time required to service the equipment. Seal circuits being serviced and charge with dry nitrogen to prevent oil contamination when timely repairs cannot be completed.

### INTRODUCTION

The Carrier VFD option Start-Up and Service Manual is intended for trained and qualified service personnel and is to be used during start-up, operation, and maintenance of Rockwell/Allen-Bradley PF755L drive.

#### ABBREVIATIONS AND EXPLANATIONS

Frequently used abbreviations in this manual include:

CCM — Chiller Control Module
DC — Direct Current
DPI — Drive Peripheral Interface

**ENET** — Ethernet

HMI — Human Machine Interface

ICVC — International Chiller Visual Controller IGBT — Insulated Gate Bipolar Transistor

I/O — Inputs/Outputs
IP — Internet Protocol
MCB — Main Control Board
MOV — Metal Oxide Varistor
— Protective Earthing O

PE — Protective Earthing Conductor
PIC — Product Integrated Control
PWM — Pulse Width Modulation
SIO — Sensor Input/Output
STS — Status

STS — Status

VFD — Variable Frequency Drive

### **Required Publications**

The Carrier VFD option Start-Up and Service Manual must be used with the following manuals:

- Latest version of the PowerFlex 755 AC Drives manuals
- Latest revision of the Start-Up, Operation, and Maintenance Instructions for the 19XRV or 23XRV with PIC6 Controls

### **Getting Assistance from Rockwell Automation**

Contact the local Rockwell Automation sales office with any questions or problems relating to the products described in this manual. For technical support on drives, call the HVAC Hotline at 1-888-926-6786, Option 1.

Before calling, have the following information available from the Allen-Bradley data nameplate located inside the enclosure on the right wall. See Fig. 1.

- Allen-Bradley ID or CAT. NO.
- Carrier VFD Code (Carrier Part Number)
- Allen-Bradley serial number

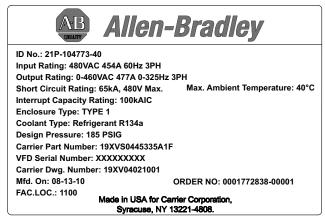


Fig. 1 — Allen Bradley Data Nameplate

### **IDENTIFYING DRIVE COMPONENTS**

Chiller control schematics and VFD schematics are included in Appendix A.

### **↑** WARNING

DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five (5) minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter rated for the DC bus voltage to ensure the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bodily injury or loss of life.

An isolated multimeter will be needed to measure DC bus voltage and to make resistance checks. The drive's DC bus capacitors retain hazardous voltages after input power has been disconnected.

### Opening the VFD Access Door

### **↑** WARNING

Before removing the drive enclosure, open access door and verify that the DC bus voltage has dropped to zero by checking the terminals behind the access door. Failure to observe this precaution could result in severe bodily injury or loss of life.

- 1. Using recommended screwdriver (6.4 mm [0.25 in.] flat or T20 star), open access door. See Fig. 2.
- 2. Check to be sure that the voltage between DC+ and DCand from each DC terminal to the chassis is zero before proceeding. See Fig. 3.

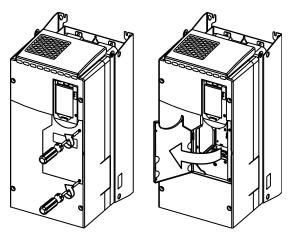


Fig. 2 — Opening Access Door

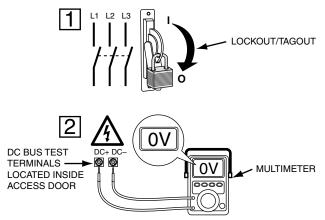


Fig. 3 — Check DC Bus Terminals

### **Drive Assembly Catalog Number**

See Fig. 4 and 5 for examples of the Rockwell Automation Drive Assembly Catalog Number.

### **Components and Physical Data**

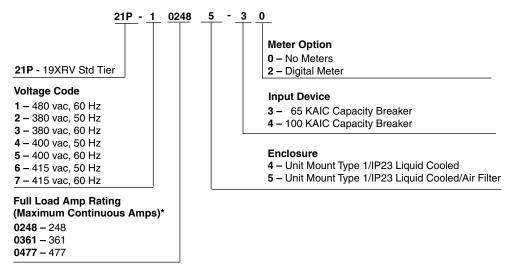
The 19XRV chillers use the Allen-Bradley PF755 Frame 6 drive for the 230-amp rated application (Carrier Part No. 19XVR0230...). See Fig. 6.

The Allen-Bradley PF755 Frame 7 drive is used for the 335-amp and 445-amp rated application (Carrier Part No. 19XVR0335... and 19XVR0445...). See Fig. 7.

See Fig. 8 for the dimensions of Frames 6 and 7 for 19XRV chillers.

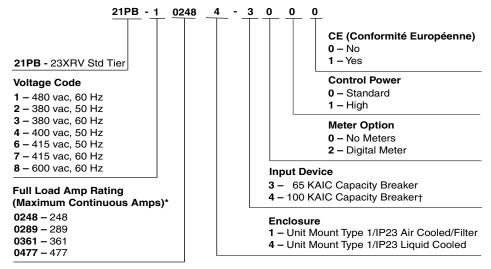
The 23XRV chiller uses the Frame 7 drive for 335-amp and 455-amp rated applications (Carrier Part No. 23XVR0335... and 23XVR0445...). Frame 6 is not used.

See Fig. 9 for the dimensions of Frame 7 for 23XRV chillers.



For Carrier applications, maximum continuous amp ratings are 230, 335, and 445.

Fig. 4 — Rockwell Automation Drive Assembly Catalog Number Nomenclature: 19XRV Units



<sup>\*</sup> For Carrier applications, maximum continuous amp ratings are 230, 269, 335, and 445.

Fig. 5 — Rockwell Automation Drive Assembly Catalog Number Nomenclature: 23XRV Units

<sup>†</sup> For 600 v applications, CB1 = 65 KAIC and CB2 = 42 KAIC rating (575 v).

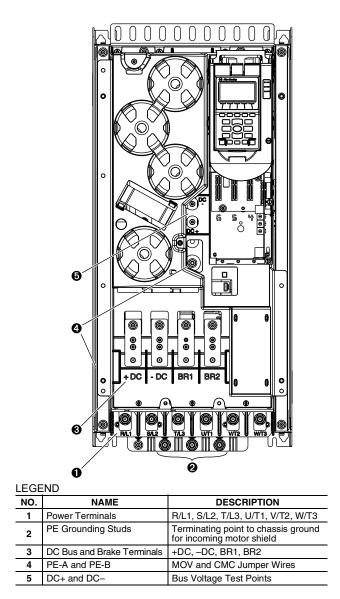
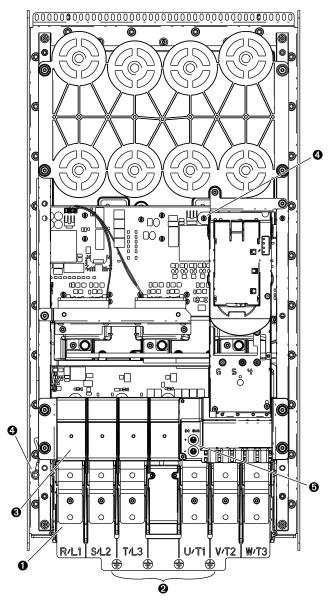


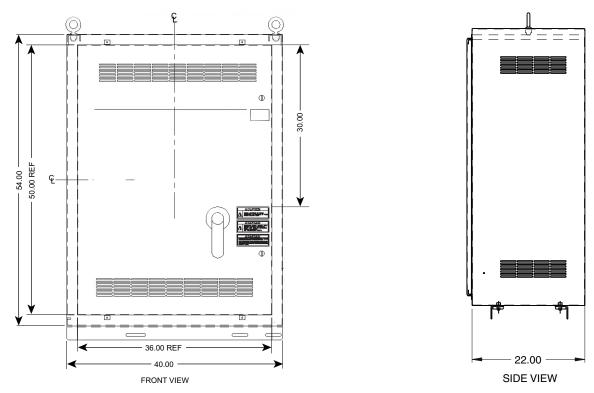
Fig. 6 — Frame 6 Drive Components



### **LEGEND**

LLOL	.110	
NO.	NAME	DESCRIPTION
1	Power Terminals	R/L1, S/L2, T/L3, U/T1, V/T2, W/T3
2	PE Grounding Studs	Terminating point to chassis ground for incoming motor shield
3	DC Bus and Brake Terminals	+DC, -DC, BR1, BR2
4	PE-A and PE-B	MOV and CMC Jumper Wires
5	DC+ and DC-	Bus Voltage Test Points

Fig. 7 — Frame 7 Drive Components



NOTE: Dimensions shown in inches.

Fig. 8 — 19XRV Enclosure Dimensions — Frames 6 and 7

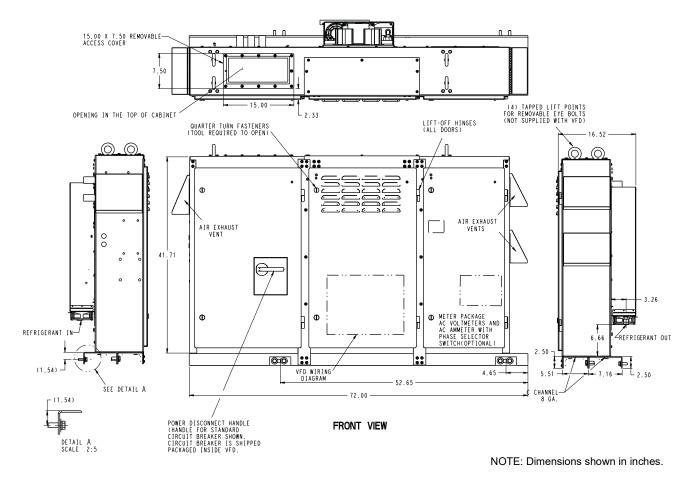


Fig. 9 — 23XRV Enclosure Dimensions — Frame 7

### START-UP

### **⚠ DANGER**

Internal components and circuit boards of the drive are live when the drive is connected to incoming power. Coming into contact with this voltage is extremely dangerous and will result in severe personal injury or death.

The motor terminals U, V, W and the DC-link/brake resistor terminals B+/R+, R- are live when the drive is connected to incoming power, even if the motor is not running.

Do not make any connections when the drive is connected to the incoming power.

After having disconnected the drive, wait until the indicators on the keypad go out (if no keypad is attached see the indicator through the keypad base). Wait 5 more minutes before doing any work on drive connections. Do not even open the cover before this time has expired.

Before connecting the drive to the incoming power, make sure that the switchgear enclosure door is closed.

### **MARNING**

The control I/O-terminals are isolated from the mains potential. However, the relay outputs and other I/O terminals may have a dangerous control voltage present even when the drive is disconnected from incoming power. Coming into contact with this voltage could result in severe personal injury.

### **A** CAUTION

If other than refrigerant cooling is used, before connecting the drive to the incoming power, make sure that the coolant is circulating and has no leaks.

### **A** CAUTION

When working with the Drive Explorer, *never* use the Rotate function as the motor will immediately start and severe compressor damage could result.

### **Alternate Wire Lugs**

If the incoming power wire size does not fit the standard lug, alternate lugs may be used. See Table 1. Note that lugs rated for a higher current than the circuit breaker may be used.

### **Verify Installation**

Record the following job information:

- 1. Job Name
- Job Number
- 3. City
- 4. State
- 5. Zip Code

Record the following nameplate information:

- 1. From the Allen-Bradley nameplate (Fig. 1) located inside the VFD enclosure:
  - a. Allen-Bradley ID or CAT NO.
  - b. Allen-Bradley Serial Number
  - c. Carrier Part Number
- From the machine nameplate (Fig. 10) located inside the VFD enclosure:
  - a. Chiller Serial Number
  - b. Chiller Model
  - c. Motor rated load amps
  - d. Motor nameplate rpm
  - e. Motor nameplate kW
  - f. Motor nameplate voltage
  - g. Inverter PWM (pulse width modulation) frequency
  - h. Voltage
- From the drive module label (Fig. 11) located on the drive module:
  - a. Model or Cat. Number
  - b. Serial Number
- 4. From the HMI control panel screen:
  - a. Carrier Part Number and Revision
  - b. Software Number

### Table 1 — Wire Lugs

VOLTAGE	CARRIER VFD MAX INPUT AMPS	STANDARD ABB LUG	STANDARD LUG CABLE RANGE	ALTERNATE ABB LUG	ALTERNATE LUG CABLE RANGE
	230	KT5300	(1) 250 - 500 MCM	KT5400	(2) 3/0 - 250 MCM
480	335	K6TJ	(3) 2/0 - 400 MCM	K6TH	(2) 250 - 500 MCM
	445	K6TJ	(3) 2/0 - 400 MCM	K6TH	(2) 250 - 500 MCM
380/400/415	230	KT5400	(2) 3/0 - 250 MCM	KT5300	(1) 250 - 500 MCM
	335	K6TJ	(3) 2/0 - 400 MCM	K6TH	(2) 250 - 500 MCM
	445	K6TJ	(3) 2/0 - 400 MCM	K6TH	(2) 250 - 500 MCM
600	269	KT5300	(1) 250 - 500 MCM	KT5400	(2) 3/0 - 250 MCM

Carrier  A United Technologies Company	
MODEL NUMBER	
SERIAL NUMBER	
MACHINE NAMEPLATE SUPPLY DATA	
VOLTS/PHASE/HERTZ	
LOCKED ROTOR AMPS	
OVERLOAD TRIP AMPS	
MAX FUSE/CIRCUIT BREAKER SIZE	
MIN SUPPLY CIRCUIT AMPACITY	
MACHINE ELECTRICAL DATA	
MOTOR NAMEPLATE VOLTAGE	
COMPRESSOR 100% SPEED	
RATED LINE VOLTAGE	
RATED LINE AMPS	
RATED LINE KILOWATTS	
MOTOR RATED LOAD KW	
MOTOR RATED LOAD AMPS	
MOTOR NAMEPLATE AMPS	
MOTOR NAMEPLATE RPM	
MOTOR NAMEPLATE KW	
INVERTER PWM FREQUENCY	
SAFETY CODE CERTIFICATION THE COMPRESSOR MOTOR CONTROLLER AND OVERLOAD PROTECTION MUST BE IN ACCOMPANCE MITH CARRIER SPECIFICATION 2-420.  192003000701 RE	

Fig. 10 — Machine Nameplate

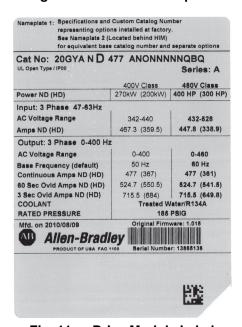


Fig. 11 — Drive Module Label

### Configure the VFD

All configurations required by the VFD are supplied by the HMI through the VFD Gateway. The 19XRV, 23XRV Std Tier VFD can operate with PIC III and PIC6. Any configuration changes necessary and possible are made on the HMI screens. A complete set of configurations is transmitted to the VFD each time the controls are powered up.

Table 2 lists parameters displayed on the 19XRV, 23XRV/VFD\_CONF screen. Table 3 shows parameters in the Unit Mounted VFD Configuration menu for PIC6. Parameters in *italics* are to be entered or confirmed at start-up. Parameters in **bold** are to be changed only after consulting with Carrier service engineering.

Table 2 — VFD Configurations (23XRV PIC6/Drive A Configuration) — DRVA1CFG

PARAMETER	DEFAULT VALUE
RATED LINE VOLTAGE	460
MOTOR RATED LOAD AMPS	440
MOTOR NAMEPLATE VOLTAGE	480
MOTOR NAMEPLATE CURRENT	440
MOTOR NAMEPLATE RPM	2060
MOTOR NAMEPLATE KW	265
COMPRESSOR 100% SPEED	97
COMPRESSOR UNLOAD SPD	25
COMPRESSOR START SPD	25
TORQUE LIMIT PERCENT	115
CURRENT LIMIT PERCENT	110
PWM SWITCH FREQUENCY, KHZ	2
SKIP FREQUENCY 1, HZ	30
SKIP FREQUENCY 2, HZ	30
SKIP FREQUENCY 3, HZ	30
SKIP FREQUENCY BAND, HZ	0
INCREASE RAMP TIME, S	100
DECREASE RAMP TIME, S	10

### NOTES:

- 1. Parameters in italics are to be entered or confirmed at start-up.
- Parameters in **bold** are to be changed only after consultation with Carrier service engineering.

Table 3 — VFD Configuration (19XRV/PIC6/UM VFD Configuration) CFGUMVFD — UM VFD Configuration

•	•
PARAMETER	<b>DEFAULT VALUE</b>
COMPRESSOR 100% SPEED	60
RATED LINE VOLTAGE	460
MOTOR NAMEPLATE CURRENT	200
MOTOR RATED LOAD CURRENT	200
MOTOR NAMEPLATE VOLTAGE	460
MOTOR NAMEPLATE RPM	3000
MOTOR NAMEPLATE KW	1500
SKIP FREQUENCY 1	30
SKIP FREQUENCY 2	30
SKIP FREQUENCY 3	30
SKIP FREQUENCY BAND	0
INCREASE RAMP TIME	30
DECREASE RAMP TIME	30
LINE VOLTAGE IMBALANCE%	10
LINE VOLT IMBALANCE TIME	10
LINE CURRENT IMBALANCE%	40
LINE CURRENT IMBAL TIME	10
MOTOR CURRENT IMBALANCE%	40
MOTOR CURRENT IMBAL TIME	10
SINGLE CYCLE DROPOUT	DISABLE
PWM SWITCH FREQUENCY (0=2 KHz, 1=4 KHz)	0

#### NOTES:

- 1. Parameters in italics are to be entered or confirmed at start-up.
- Parameters in **bold** are to be changed only after consultation with Carrier service engineering.

### **Commissioning the Unit**

The commission procedure is as follows:

- 1. If the chiller has been stored outdoors, allow at least 24 hours room temperature stabilization prior to commissioning. Ensure any condensation that occurs as a result of the ambient temperature is allowed to evaporate.
- 2. Enter parameters in the VFD Configuration screen.
- 3. Install surge suppression devices if required.
- 4. Review the power wiring and grounding to ensure that it has been properly connected.
- 5. Visually examine the inside of the drive enclosure to:
  - a. Look for signs of corrosion or moisture residue.
  - b. Remove any dirt or debris.
  - c. Make sure all vents are clear.
- Apply power to the drive and take thermal measurements of the capacitor bank and power connections. Do this again before start-up.
- 7. Measure and record the incoming line voltage. Line-to-line voltages should be balanced within 3% as calculated by Rockwell's procedure below:

Measure voltages phase-to-phase and phase-to-ground.

Vmax = Maximum measured phase-to-phase voltage (A to B, B to C, C to A)

Vmin = Minimum measured phase-to-phase voltage Imbalance Calculation Formula

Vavg = 
$$\frac{\text{(VAB + VBC + VCA)}}{3}$$
Imbalance % = 
$$\frac{\text{(Vmax - Vmin)} \times 100}{\text{Vavg}}$$

- 8. Take a final thermal measurement of the capacitor bank and power after finalizing the installation to ensure all connections are good.
- 9. If a ground fault occurs, then do the following:
  - a. Check for a ground in the motor or motor wiring.
  - Check wiring insulation for damage and check that wiring is dry.
  - c. Verify the motor wiring is separated from ground and there is no connection between phases.
  - d. Check for failed IGBTs.
- 10. If an overcurrent fault occurs, then do the following:
  - a. Check for excessive load and verify load limit settings on the HMI.
  - b. Check motor and wiring insulation.
  - Check parameter settings on UM VFD Configuration for PIC6.

### **Check Internal Jumpers**

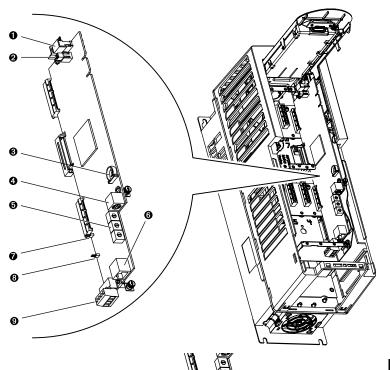
On the Main VFD Control board there are 2 jumpers labeled J1 HARDWARE ENABLE and J2 SAFETY ENABLE. J1 should be removed and J2 should be in place. See Fig. 12.

Two jumper wires connect a particular terminal to chassis ground. The MOV and AC EMI jumper should be connected to the PE-A terminal. The COMMON MODE CAPACITORS to GROUND jumper should be connected to a standoff rather than the PE-B terminal.

Use the recommended tools as follows when connecting jumper wires in Frame 6 and in Frame 7:

- Recommended torque (screws and nuts) = 1.36 N·m (120.0 lb·in.)
- Recommended hex socket = 7 mm
- Recommended screwdriver = T20 star type

See Fig. 13 and Fig. 14 for the correct positions of the jumpers.



NO.	NAME	DESCRIPTION
1	HIM (Human Interface Module) Connector	DPI Port 1 (HIM Cradle) connection.
2	Fan Connector	Power supply for internal cooling fan (Frames 2 and 3).
3	Battery Receptacle	User-installed CR1220 lithium coin cell battery provides power to the real-time clock (Optional, not supplied).
4	DPI Port 2	Cable connection for handheld and remote HIM options.
5	Embedded Ethernet/ IP Address Selectors	Rotary switches for setting lowest octet of Ethernet address (forces address to 192.168.1.xxx).
6	Embedded Ethernet/ IP Connector	Network cable connection.
7	Jumper J2 SAFETY ENABLE	Safety enable jumper. Removed when safety option is installed. NOTE: For standard Carrier PF755 application the jumper is to stay in place.
8	Jumper J1 HARDWARE ENABLE	Hardware enable jumper. Removed when a hardware enable configuration is utilized. NOTE: For standard Carrier PF755 application this jumper is removed. Ensure to remove jumper if either a replacement power module is installed or a replacement main control board is installed.
9	TB1	I/O terminal block.

IMPORTANT: Wiring to pluggable terminal block connectors should be supported by wire ties or other means to help prevent unintentional disconnection.

### **TB1 I/O TERMINAL DESIGNATIONS**

FIXED I/O	TERMINAL	NAME	DESCRIPTION
Di Oc	Di 0ac	Digital Input 120V AC	Connections for AC power supply.
	Di C	Digital Input Common	Digital input common
	Di 0dc	Digital Input 24V DC	Connections for DC power supply.
	+24V	+24 Volt Power	Connections for drive supplied 24V power.
	24VC	24 Volt Common	

Fig. 12 — PF755 Main Control Board

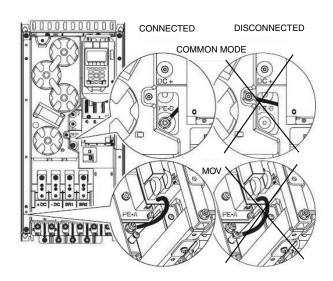


Fig. 13 — Jumper Wire Locations — Frame 6

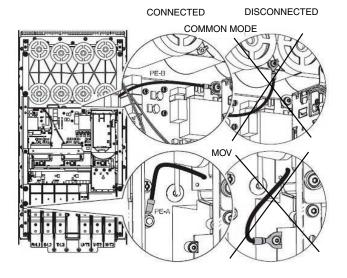


Fig. 14 — Jumper Wire Locations — Frame 7

### **SERVICE**

### **↑** WARNING

DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five (5) minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bodily injury or loss of life.

### **Troubleshooting the Drive**

The drive can display 2 kinds of error codes on the HMI called Alert and Alarm codes. These codes signal a problem detected during self-tuning or drive operation. Note the following differences between Carrier and Allen-Bradley terminology:

- A warning message on the HMI is an ALERT.
- The same warning viewed with Rockwell Drive Explorer is a VFD ALARM.
- A failure resulting in a shutdown is seen as an ALARM on the HMI and as a VFD FAULT when viewed with Drive Explorer.

**CONDITION CODES** 

CHILLER ALERT = VFD ALARM CHILLER ALARM = VFD FAULT

See Tables 4-5 and Fig. 15.

### CHILLER ALERT CODES

An alert condition is indicated by a message on the HMI screen. The drive will continue to operate during the alert condition. Investigate the cause of the alert to ensure it does not lead to a fault condition. The alert code will automatically be cleared from the HMI when the condition causing the alert no longer exists. See the 19XRV or 23XRV Start-Up, Operation and Maintenance Instructions for ICVC alert codes or appropriate Controls Operation and Troubleshooting manual for PIC6 controls.

### CHILLER ALARM CODES

An alarm condition is also indicated by a message on the HMI screen. If an alarm occurs, the drive coasts to stop. The STS (status) light on the drive will turn from green to red or yellow (see Table 4). The detected fault message is maintained on the display until it is cleared by pressing the RESET softkey. See the 19XRV or 23XRV Controls Operation and Troubleshooting manual for PIC6 controls.

### TEST EQUIPMENT NEEDED TO TROUBLESHOOT

An isolated multimeter adequately rated for the DC bus voltage will be needed to measure DC bus voltage and to make resistance checks. Note that dedicated troubleshooting test points are not provided.

#### VERIFYING DC BUS CAPACITORS ARE DISCHARGED

The drive's DC bus capacitors retain hazardous voltages after input power has been disconnected. Perform the following steps before touching any internal components:

- 1. Turn off and lock out input power. Wait 5 minutes.
- 2. Verify that there is no voltage at the drive's input power terminals.
- 3. Measure the DC bus potential with a voltmeter while standing on a non-conductive surface and wearing insulated gloves (1000 v). Measure the DC bus potential. See Fig. 6 for the 248-amp drive and Fig. 7 for the 289, 361, and 477-amp drives. The voltage between DC+ and DC-, and from each DC terminal to the chassis must be zero before proceeding.
- 4. Once the drive has been serviced, reapply input power.

### HIGH TEMPERATURE ALARMS

Coolant flow through the cold plate is controlled by an orifice in the refrigerant line leaving the cold plate. The orifice looks like one of the O-ring face seal connectors and in fact is used as one of the connections on the coolant tubing. If the orifice is present and condenser liquid flow is present, the liquid will flash to cooler temperature at the orifice. This temperature difference is great enough to be easily felt.

Table 4 —	Drive	Status	Indicator	<b>Descriptions</b>
I able T	DIIVE	Julius	Hidicator	Describilions

NAME	COLOR	STATE	DESCRIPTION		
	Green	Flashing	Drive ready but not running, and no faults are present.		
		Steady	Drive running, no faults are present.		
	Yellow	Flashing	Drive is not running. A type 2 (non-configurable) alarm condition exists, and the drive cannot be started.		
		Steady	Drive is not running, a type 1 alarm condition exists. The drive can be started.		
STS (Status)	Red	Flashing	A major fault has occurred. Drive cannot be started until fault condition is cleared.		
		Steady	A non-resettable fault has occurred.		
	Red/Yellow	Flashing Alternately	A minor fault has occurred. When running, the drive continues to run. System is brought to a stop under system control. Fault must be cleared to continue. Use parameter 950 [Minor Flt Config] to enable. If not enabled, acts like a major fault.		
	Green/Red	Flashing Alternately	Drive is flash updating.		
	None (Unlit)	Off	Adapter and/or network is not powered, adapter is not properly connected to the network or adapter needs an IP address.		
	Red	Flashing	An Ethernet/IP connection has timed out.		
ENET		Steady	Adapter failed the duplicate IP address detection test.		
	Red/Green	Flashing Alternately	Adapter is performing a self-test.		
	Green	Flashing	Adapter is properly connected but is not communicating with any devices on network.		
		Steady	Adapter is properly connected and communicating on the network.		
	None (Unlit)	Off	Adapter is not powered or is not transmitting on the network.		
LINK	Green	Flashing	Adapter is properly connected and transmitting data packets on the network.		
		Steady	Adapter is properly connected but is not transmitting on the network.		

### NOTES:

- A Type 1 alarm indicates that a condition exists. Type 1 alarms are user configurable.
- A Type 2 alarm indicates that a configuration error exists and the drive cannot be started. Type 2 alarms are not configurable.

Table 5 — PIC6 Powerflex 755 Fault Code Descriptions and Corrective Actions

VFD	23XRV	19XRV		PEODINE ION	000000000000000000000000000000000000000
FAULT CODE	FAULT STATE	FAULT STATE	FAULT TYPE	DESCRIPTION	CORRECTIVE ACTION
NONE	*	449	Nie Entre	Processor memory fault	Consult VFD manual to resolve generic fault.
2	*	439	No Entry  Auxiliary Input	Input is open.	Check Compressor Discharge High Pressure switch wiring and accuracy. Check for high condenser water temperatures, low water flow, fouled tubes. Check for division plate/gasket bypass. Check for noncondensables in refrigerant.
3	*	425	Power Loss	Line voltage dropout	Temporary loss of voltage. For 19XRV, disable Single Cycle Dropout in CFGUMVFD (PIC6) screen.
4	*	429	Undervoltage	Low DC bus voltage	Verify phase-to-phase and phase-to-ground line voltage. VFD Circuit Board malfunction. Contact Carrier Service.
5	*	430	Overvoltage	High DC bus voltage	Verify phase to phase and phase to ground line voltage. Monitor AC line for high transient voltage conditions.
7	*	434	Motor Overload	An internal electronic overload trip has occurred.	Any phase current > 106% RLA. Can result from significant load side current imbalance when running at full load. Check entering condenser water temperature and water flow rate. Check Motor Rated Load Amps in CFGUMVFD (PIC6) screen.
8	*	444	Heat Sink Overtemp	Heat sink temperature has exceeded maximum operating temperature.	Check that VFD refrigerant isolation valves are open. Check VFD refrigerant cooling orifice and refrigerant strainer. Check for proper VFD cooling fan operation and air flow blockage.
9	*	444	Transistor Overtemp	The output transistors have exceeded maximum operating temperature.	Check that VFD refrigerant isolation valves are open. Check VFD refrigerant cooling orifice and refrigerant strainer. Check for proper VFD cooling fan operation and air flow blockage.
12	*	438	HW Overcurrent	The drive output current has exceeded hardware current limit.	Check for high entering water temperature or low condenser water flow. For 19XRV, check current settings in CFGUMVFD screen. For 23XRV, check current settings.
13	*	432	Ground Fault	A current path to earth ground greater than 25% of drive rating has occurred.	Check the motor, motor terminals, and external wiring to the drive output terminals for a grounded condition.
14	*	432	Ground Warning	The ground current has exceeded the level set in P467.	_
15	*	449	Load Loss	If this fault appears, there may be a prob- lem with software configuration.	To reset the processor, cycle power to chiller, check settings and save settings when exiting CFGUMVFD (PIC6) configuration screen. Check VFD parameters with Drive Explorer.
17	*	446	The DC bus ripple has exceeded a preset level.	Line Voltage imbalance	Check phase-to-phase and phase-to-ground distribution bus voltage. For 19XRV, increase Line Voltage % Imbalance in CFGUMVFD (PIC6) screen.
20	*	449	TorqPrv Spd Band	See VFD Fault Code 15	See VFD Fault Code 15
21	*	445	Output PhaseLoss	The current in one or more phases has been lost or remains below a preset level.	For 19XRV, check Motor Current % Imbalance in CFGUMVFD (PIC6) screen.
24	*	442	Decel Inhibit	The drive is not following a commanded deceleration because it is attempting to limit bus voltage.	Verify input voltage is within drive specified limits. Verify system ground impedance follows proper grounding techniques. Disable bus regulation P186 and/or add dynamic brake resistor and/or extend deceleration time P537 and P538.
33	*	449	AuRsts Exhausted	See VFD Fault Code 15	See VFD Fault Code 15
36	*	438	SW Overcurrent	The drive output current has exceeded the 1 ms current rating.	Check for excess load, improper DC boost setting, DC brake volts set too high.
38			Phase U to Gnd		Check wiring between drive and motor. Check
39 40	*	432	Phase V to Gnd Phase W to Gnd	GROUND FAULT	motor for grounded phase. Check motor terminals. Replace drive.
41			Phase W to Gnd Phase UV Short		- p
42	*	449	Phase VW Short Phase WU Short	GROUND FAULT	Check wiring between drive and motor. Check motor terminals. Replace drive.
44	*	432	Phase UNot ToGnd		
45	*	432	Phase VNot ToGnd	GROUND FAULT (no LF2 equivalent)	Check wiring between drive and motor. Check motor terminals. Replace drive.
46	*	432	Phase WNot		· ·
55	*	444	Overtemp	The temperature sensor on the main control board detected excessive heat.	Check that VFD refrigerant isolation valves are open. Check VFD refrigerant strainer.
61	*	449	Shear Pin 1	See VFD Fault Code 15	See VFD Fault Code 15
62	· ·	449	Shear Pin 2	See VFD Fault Code 15	See VFD Fault Code 15

Table 5 — PIC6 Powerflex 755 Fault Code Descriptions and Corrective Actions (cont)

VFD FAULT CODE	23XRV FAULT STATE	19XRV FAULT STATE	FAULT TYPE	DESCRIPTION	CORRECTIVE ACTION
64	*	449	Drive Overload	Drive is overloaded.	Check for high entering water temperature or low condenser water flow. Check current settings in CFGUMVFD (PIC6) screen.
77	*	449	IR Volts Range	See VFD Fault Code 15	See VFD Fault Code 15
78	*	449	FluxAmpsRef Rang	See VFD Fault Code 15	See VFD Fault Code 15
79	*	449	Excessive Load	Motor did not come up to speed in the allotted time.	Check that guide vanes are closed completely. Check for high entering water temperature or low condenser flow. Repeat Autotune
80	*	449	AutoTune Aborted	See VFD Fault Code 15	See VFD Fault Code 15
87	*	449	IXo VoltageRange	Ixo voltage calculated from motor name- plate data is too high.	Re-enter motor nameplate data in CFGUMVFD (PIC6) screen.
91	*	449	Pri VelFdbk Loss	See VFD Fault Code 15	See VFD Fault Code 15
93	*	449	HW Enable Check	See VFD Fault Code 15	See VFD Fault Code 15
94	*	449	Alt VelFdbk Loss	See VFD Fault Code 15	See VFD Fault Code 15
95	*	449	Aux VelFdbk Loss	See VFD Fault Code 15	See VFD Fault Code 15
96	*	449	PositionFdbkLoss	See VFD Fault Code 15	See VFD Fault Code 15
97	*	449	Auto Tach Switch	See VFD Fault Code 15	See VFD Fault Code 15
100	*	451	Parameter Chksum	The checksum read from the board does not match the checksum calculated.	Press Reset alarm (PIC6). Check VFD Configuration parameters. Cycle power to the drive.
106	*	453	Incompat MCB-PB	The main control board did not recognize the power structure.	Flash with newer Application version software.
107	*	451	Replaced MCB-PB	The main control board was moved to a different power structure. Data set to default values.	Press Reset alarm (PIC6). Check CFGUMVFD (PIC6) parameters. Cycle power to the drive.
113	*	451	Tracking DataErr	Internal data error	Press Reset alarm (PIC6). Cycle power to the drive.
124	*	451	App ID Changed	Application firmware changed.	Verify application version.
141	*	449	Autn Enc Angle	P78 [Encdrlss AngComp] is out of range.	See VFD Fault Code 15
142	*	449	Autn Spd Rstrct	See VFD Fault Code 15	See VFD Fault Code 15
143	*	449	Autotune CurReg	See VFD Fault Code 15	See VFD Fault Code 15
144	*	449	Autotune Inertia	See VFD Fault Code 15	See VFD Fault Code 15
145	*	449	Autotune Travel	See VFD Fault Code 15	See VFD Fault Code 15
168	*	444	HeatSinkUnderTmp	Heatsink temperature sensor is reporting a value below –18.7°C (–1.66°F) or the sensor feedback circuit is open.	Check heat sink temperature sensor. Check heat sink temperature.
210	*	449	HW En Jumper Out	See VFD Fault Code 15	See VFD Fault Code 15
211	*	449	Safety Brd Fault	See VFD Fault Code 15	See VFD Fault Code 15
213	*	449	Safety Jumper In	See VFD Fault Code 15	See VFD Fault Code 15
226	*	448	VFD Comm loss	The device at the port has stopped communicating with the main control board.	Verify that the device is present and functional. Verify network connections. Verify options installed in appropriable ports are seated in the port and secured with mounting screws.
291	*	449	HSFan Lifwe	See VFD Fault Code 15	See VFD Fault Code 15
292	*	449	InFan Life	See VFD Fault Code 15	See VFD Fault Code 15
293	*	449	MtrBrg Life	See VFD Fault Code 15	See VFD Fault Code 15
294	*	449	MtrBrg Lube	See VFD Fault Code 15	See VFD Fault Code 15
295	*	449	MachBrg life	See VFD Fault Code 15	See VFD Fault Code 15
296	*	449	MachBrg Lube	See VFD Fault Code 15	See VFD Fault Code 15
315	*	449	Excess Psn Error	See VFD Fault Code 15	See VFD Fault Code 15
351	*	426	In Cur Share L1	An input current sharing imbalance between parallel converters in this AC line is greater than 15% of converter rated current	See VFD Fault Code 15
352	*	426	In Cur Share L2	An input current sharing imbalance between parallel converters in this AC line is greater than 15% of converter rated current	See VFD Fault Code 15
353	*	426	In Cur Share L3	An input current sharing imbalance between parallel converters in this AC line is greater than 15% of converter rated current	See VFD Fault Code 15

<sup>\* 23</sup>XRV PIC6 will display the actual PF755 fault code on the touch screen as the fault occurs. The PIC6 state/alarm code will be generic ALM 801 through 806 in the PIC6 Alarm History and the PF755 VFD fault code will be shown as part of the PIC6 ALM-801 description. An example would be "ALM 801 VFD Fault - (8) Heat Sink Overtemp".

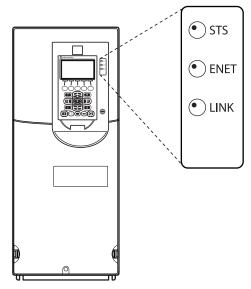


Fig. 15 — Drive Status Indicator

### MAIN CONTROL BOARD (MCB) COMPONENTS

Figure 16 shows the drive module with the cover removed. To access the control boards, loosen the screw on the face of the keypad mount and swing the keypad mount upward.

The components on the main control board (MCB) are shown in Fig. 17. Note the location of the terminals labeled MCB I/O. The high-pressure switch is wired to these terminals as shown in Fig. 18. In the event of a high condenser pressure alarm, the connections at these terminals should be checked and tightened if necessary.

Typical wiring schematics are shown in Appendix A.

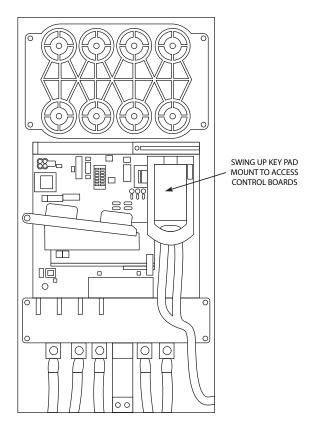


Fig. 16 — Drive Module with Cover Removed

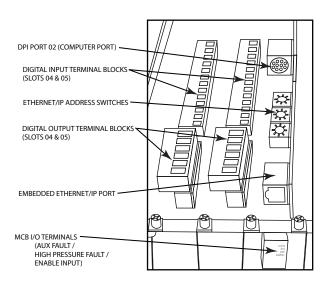
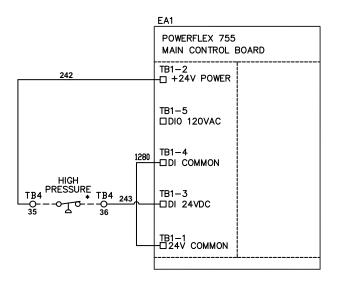


Fig. 17 — MCB (Main Control Board) Components



<sup>\*</sup>Located outside of starter; connected by field wiring.

### Fig. 18 — High-Pressure Switch Wiring

### **Checking Power Modules and Motor Input with Input Power Off**

Use the following procedure to check the drive's power module circuitry with power off:

- 1. Turn off and lock out input power. Wait 5 minutes.
- 2. Verify there is no voltage at the drive's input power terminals.
- Using a voltmeter, check the DC bus potential as described in the section Verifying That DC Bus Capacitors Are Discharged on page 11 to ensure the DC bus capacitors are discharged.
- 4. Disconnect the motor from the drive.
- 5. Check all AC line and DC bus fuses.
- 6. Use a multimeter to check the input diodes and output IGBTs if a fuse is open. See Table 6.
- 7. Check motor impedance.
- 8. Reconnect the motor to the drive.
- Reapply input power.

### **↑** WARNING

DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five (5) minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before touching any internal components. Confirm that the DC bus has discharged before performing diode checks. Failure to observe this precaution could result in severe bodily injury or loss of life.

Table 6 — Diode Checks

METER LEAD		METER READING	
(+)	(-)	METER READING	
R	DC+	0.5 v	
H	DC-	Infinite (OL)	
S	DC+	0.5 v	
<u> </u>	DC-	Infinite (OL)	
Т	DC+	0.5 v	
	DC-	Infinite (OL)	
U	DC+	0.5 v	
	DC-	Infinite (OL)	
V	DC+	0.5 v	
V	DC-	Infinite (OL)	
W	DC+	0.5 v	
VV	DC-	Infinite (OL)	
	R		
	S		
DC+	Т	Infinite (OL)	
DO+	U	minite (OL)	
	V	Ì	
	W		
DC-	R		
	S		
	T	0.5 v	
	U	0.5 V	
	V		
	W		

NOTE: Digital meters require a special diode check function because the current sourced by the meter during a normal resistance (Ohms) test is too low to accurately test a diode. Make sure the meter is set to the diode test function. Voltage readings may not be exact as shown in above table, but look for consistency during each of the 4 tests. When performing a test that should return infinity (OL) as shown in above table, you may see a value slowly climbing toward infinity. This is a result of the meter charging a capacitor and is normal.

### Servicing the Drive

### **MARNING**

To guard against possible personal injury and/or equipment damage:

- 1. Inspect all lifting hardware for proper attachment before lifting drive.
- Do not allow any part of the drive or lifting mechanism to make contact with electrically charged conductors or components.
- 3. Do not subject the drive to high rates of acceleration or deceleration while transporting to the mounting location or when lifting.

Do not allow personnel or their limbs directly underneath the drive when it is being lifted and mounted.

### **⚠ WARNING**

DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five (5) minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bodily injury or loss of life.

- 1. Using recommended screwdriver (6.4 mm [0.25 in.] flat or T20 star), open access door. See Fig. 19.
- 2. Check to be sure that the voltage between DC+ and DCand from each DC terminal to the chassis is zero before proceeding. See Fig. 20.
- 3. Remove the enclosure. See Fig. 21.

### REMOVING THE DRIVE

The dimensions and weights specified must be taken into consideration when removing the drive. All lifting equipment and lifting components (hooks, bolts, lifts, slings, chains, etc.) must be properly sized and rated to safely lift and hold the weight of the drive while removing it. For 19XRV chillers, see Fig. 22. For 23XRV chillers, see Fig. 23. The drive weights are as follows:

- Drive weight for Frame 6: 85 lb.
- Drive weight for Frame 7: 160 249 lb.

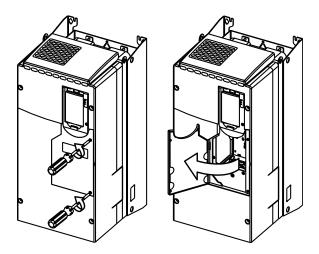


Fig. 19 — Open Access Door

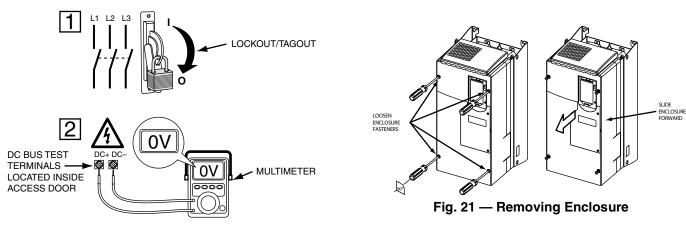


Fig. 20 — Check DC Bus Terminals

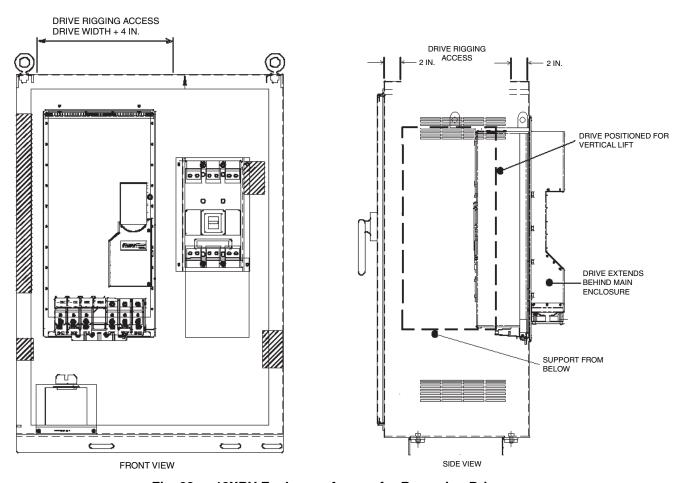


Fig. 22 — 19XRV Enclosure Access for Removing Drive

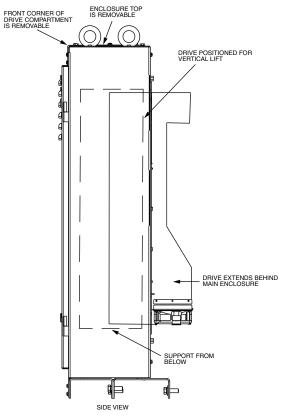


Fig. 23 — 23XRV Enclosure Access for Removing Drive

When replacing the drive, reverse the procedures and tighten to the torques for Frames 6 and 7 power terminal block listed in Table 7.

Table 7 — Frames 6 and 7 Power Terminal Block

FRAME	MAXIMUM LUG WIDTH	RECOMMENDED TORQUE	TERMINAL BOLT SIZE
6	34.6 mm (1.36 in.)	11.3 N·m (100 inlb)	M8 x 1.25
7	43.5 mm (1.71 in.)	11.3 N·m (100 inlb)	M8 x 1.25

### RIGGING THE ENCLOSURE

Where overhead room and/or clearance in front of the drive enclosure is insufficient to allow the drive to be safely removed from the enclosure, the entire enclosure may have to be removed from the chiller.

The dimensions and weights specified must be taken into consideration when removing the enclosure. For 19XRV chillers, the total weight for Frames 6 and 7, including drive weight and enclosure, is 720 lb. The 23XRV chiller enclosure, including all components, weighs 975 lb. All lifting equipment and lifting components (hooks, bolts, lifts, slings, chains, etc.) must be properly sized and rated to safely lift and hold the weight of the enclosure and drive while removing. See Fig. 24 and Fig. 25.

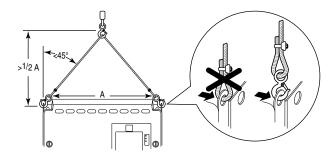


Fig. 24 — Rigging the Enclosure, Frame 6

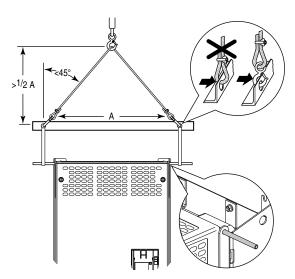
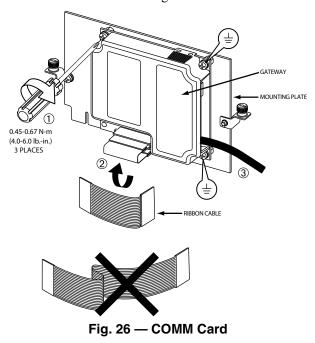


Fig. 25 — Rigging the Enclosure, Frame 7

### REPLACING GATEWAY 20-COMM-H OPTION CARD

Follow these steps for removing and replacing existing gateway:

- 1. Disconnect power to the drive. Before removing the enclosure, open the access door on the front of the drive. See Fig. 19.
- 2. Check to be sure that the voltage between DC+ and DC- and from each DC terminal to the chassis is zero before proceeding. See Fig. 20.
- 3. Remove the enclosure. See Fig. 21.
- 4. Remove the 2 screws securing the mounting plate and remove the mounting plate and COMM card. See Fig. 26.
- 5. Mount the new COMM card and mounting plate and attach with the 2 screws removed in Step 4. See Fig. 27.
- Use the shorter ribbon cable to connect the plug on the COMM card to the connector on the mounting plate. See Fig. 26.
- 7. Install the enclosure. See Fig. 21.



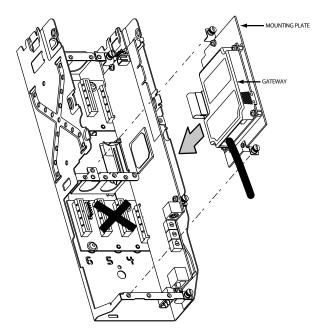


Fig. 27 — Mount COMM Card Plate to Drive

### REPLACING CHILL PLATE FAN AND INTERNAL FAN

Follow these steps to replace the chill plate fan and internal fan in Frames 6 and 7.

### Frame 6 (chill plate fan kit Z1P-FAN-A6-A):

- Disconnect power to the drive. Before removing the enclosure, open the access door on the front of the drive. See Fig. 19.
- 2. Check to be sure that the voltage between DC+ and DC- and from each DC terminal to the chassis is zero before proceeding. See Fig. 20.
- 3. Remove the enclosure. See Fig. 21.
- 4. Remove and replace the chill plate fan. See Fig. 28.
- 5. Remove and replace the internal fan. See Fig. 29.
- 6. Install the enclosure. See Fig. 21.

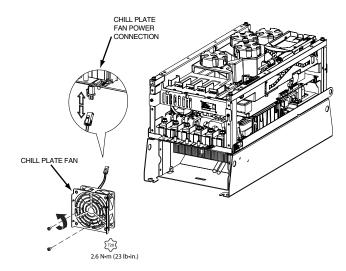


Fig. 28 — Chill Plate Fan, Frame 6

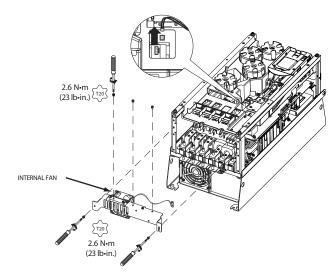


Fig. 29 — Internal Fan, Frame 6

### Frame 7 (chill plate fan kit Z1P-FAN-A7-A):

- 1. Disconnect power to the drive. Before removing the enclosure, open the access door on the front of the drive. See Fig. 19.
- 2. Check to be sure that the voltage between DC+ and DCand from each DC terminal to the chassis is zero before proceeding. See Fig. 20.
- 3. Remove the enclosure. See Fig. 21.
- 4. Remove and replace the chill plate and internal fans. See Fig. 30.
- 5. Install the enclosure. See Fig. 21.

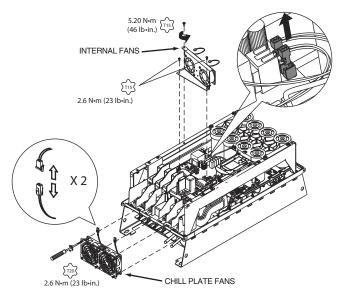


Fig. 30 — Chill Plate and Internal Fans, Removal and Replacement, Frame 7

### **Part Identification and Location**

See Fig. 31-34 for parts descriptions and locations.

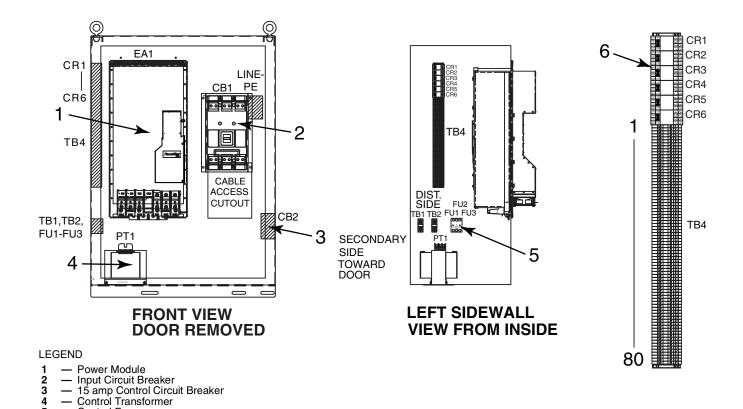
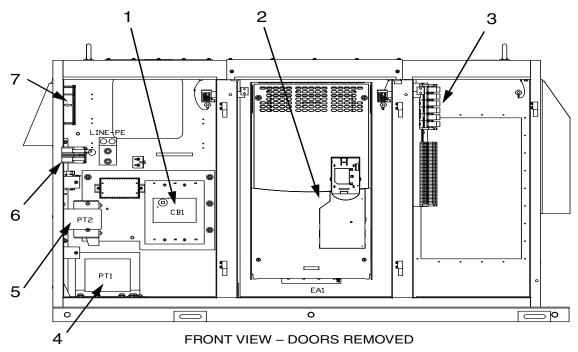


Fig. 31 — 19XRV Assembly Parts



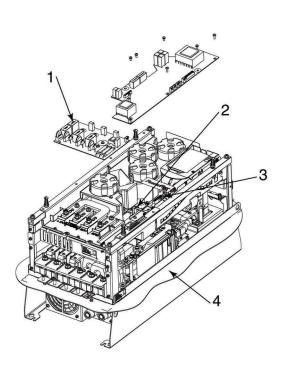
### **LEGEND**

Input Circuit BreakerPower Module

Control Fuses
 Control Relays (CR1 - CR6)

- Control Relays (CR1 CR6)
   120 v Control Transformer
   120 v Vaporizer Heater Transformer
   15 amp Control Circuit Breaker
   Cooling Fan

Fig. 32 — 23XRV Assembly Parts



IMPORTANT: When replacing the Main Control Board (Item No. 5) or the entire power module, the jumper marked "J1 HARDWARE ENABLE" must be removed and the jumper marked "J2 SAFETY ENABLE" must be left in place.

### **LEGEND**

- PF750 Series, Precharge Kit
- PF750 Series, Gate Interface
   PF750 Series, Power Interface
   PowerFlex 750 Series, Flange Gasket
- PF755 Main Control Board
- PF750 Series, Backplane Interface
   PF750 Series, Type 4X/12 Chill Plate (Heatsink) Fan Kit
- Chill Plate Fan

Fig. 33 — Frame 6 Parts

### **LEGEND**

- 1 Slot for Gateway (Gateway Not Shown)
  2 PF750 Series, Backplane Interface
  3 PF750 Series, Type 4X/12 Heatsink Fan Kit
  4 PF750 Series, Power Interface
  5 PF750 Series, Bus Cap Assembly
  6 PF750 Series, Power Interface Cable
  7 PF750 Series, Current Transducer Kit

- 7 PF750 Series, Current Transducer Kit
  8 PF750 Series, Precharge Kit
  9 Slot for 24 v I/O Module (24 v I/O Module Not Shown)
- 10 PF755 Main Control Board

IMPORTANT: When replacing the Main Control Board (Item No. 10) or the entire power module, the jumper marked "J1 HARDWARE ENABLE" must be removed and the jumper marked "J2 SAFETY ENABLE" must be left in place.

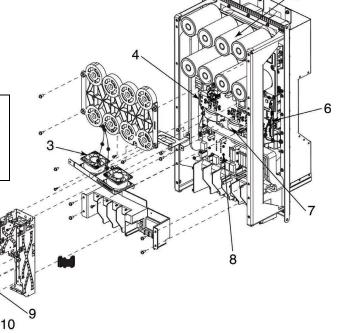
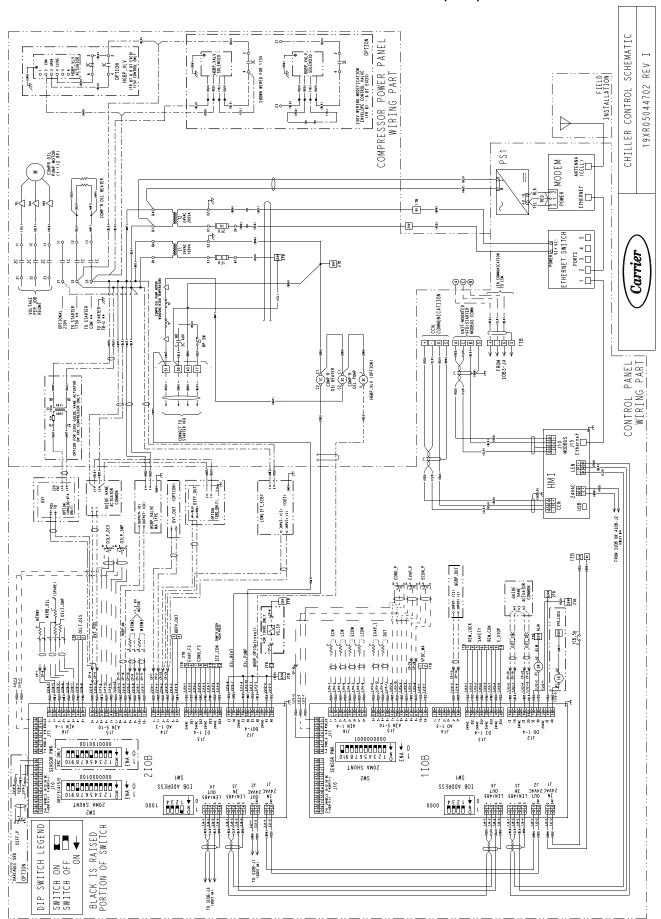
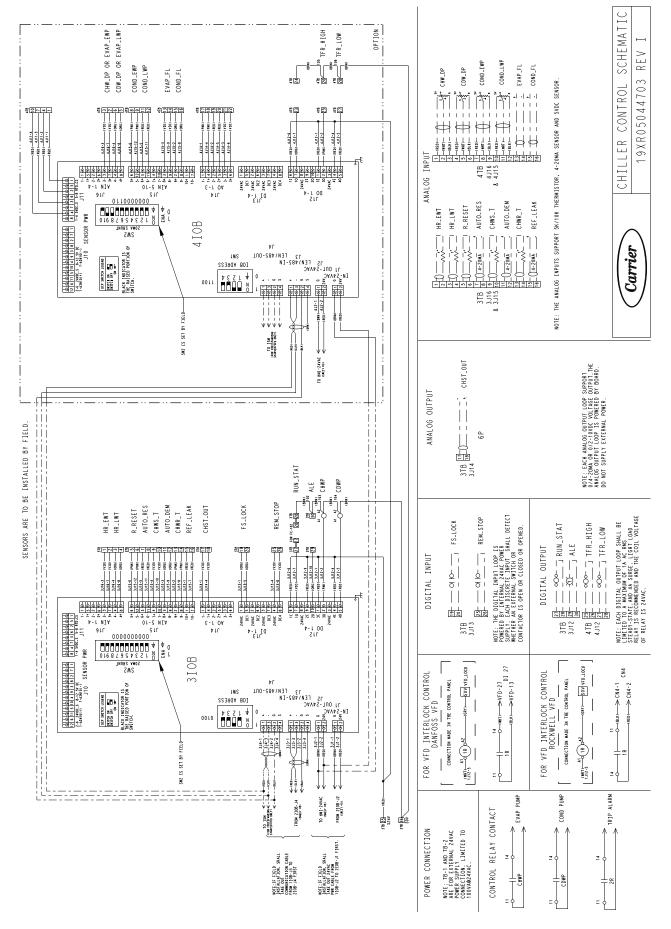


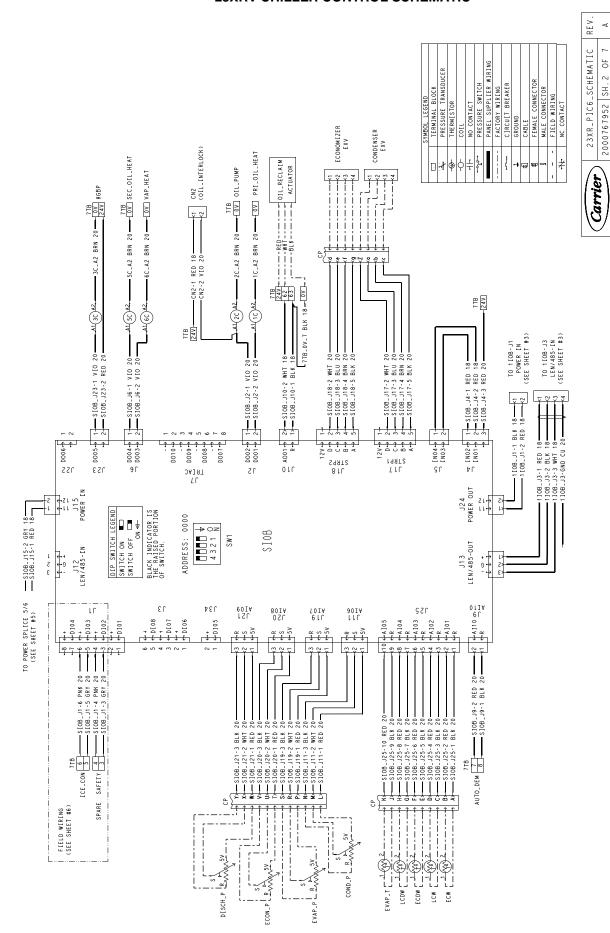
Fig. 34 — Frame 7 Parts

### APPENDIX A — WIRING SCHEMATICS 19XRV CHILLER CONTROL SCHEMATIC (PIC6)



### APPENDIX A — WIRING SCHEMATICS (CONT) 19XRV CHILLER CONTROL SCHEMATIC (PIC6) (cont)



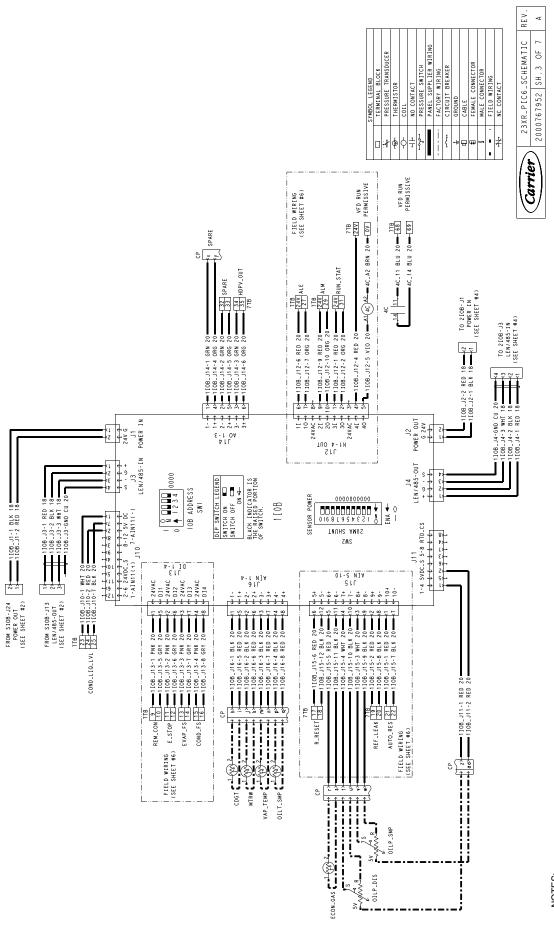


NOTES:

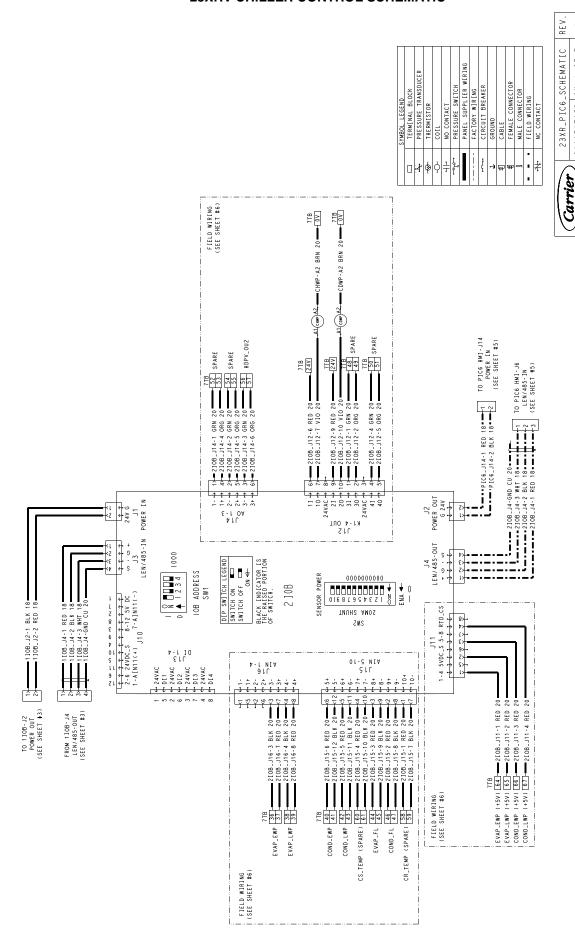
1. Liquid flow circuit: to install optional flow device, wire as shown (NO) and replace jumper with a 4.3k resistor.

2. For TP compressor, the condenser flow switch must be installed in series with the cooler flow switch. Do not connect condenser flow switch to J3 (Lower) 23 and 24.

3. For TP compressor, remove 4.3k resistor between J3 (Lower) 20 and 21.



Liquid flow circuit: to install optional flow device, wire as shown (NO) and replace jumper with a 4.3k resistor. For TP compressor, the condenser flow switch must be installed in series with the cooler flow switch. Do not connect condenser flow switch to 31 (Lower) 23 and 24. For TP compressor, remove 4.3k resistor between J3 (Lower) 20 and 21. 7 ω.



SH. 4 OF 7

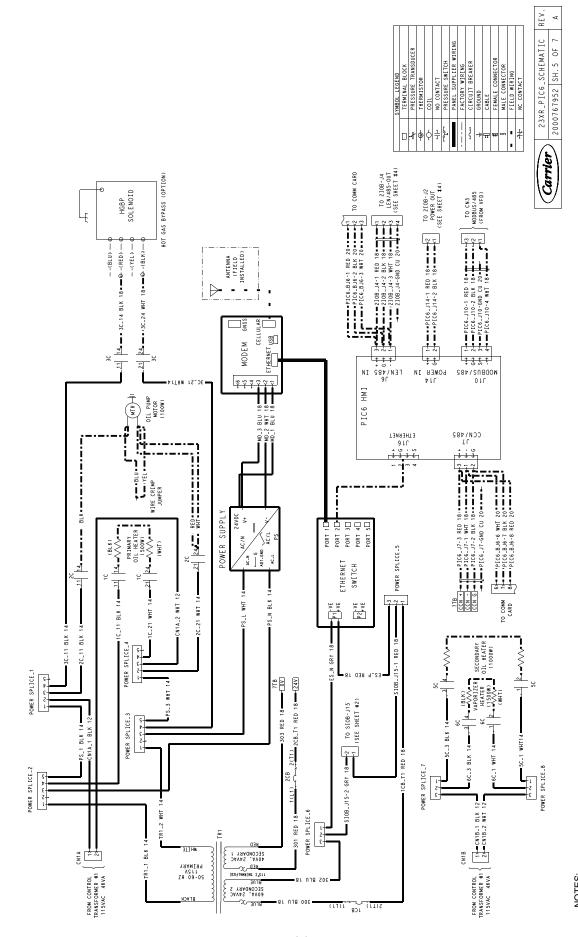
2000767952

NOTES:

1. Liquid flow circuit: to install optional flow device, wire as shown (NO) and replace jumper with a 4.3k resistor.

2. For TP compressor, the condenser flow switch must be installed in series with the cooler flow switch. Do not connect condenser flow switch to 33 (Lower) 23 and 24.

3. For TP compressor, remove 4.3k resistor between J3 (Lower) 20 and 21.



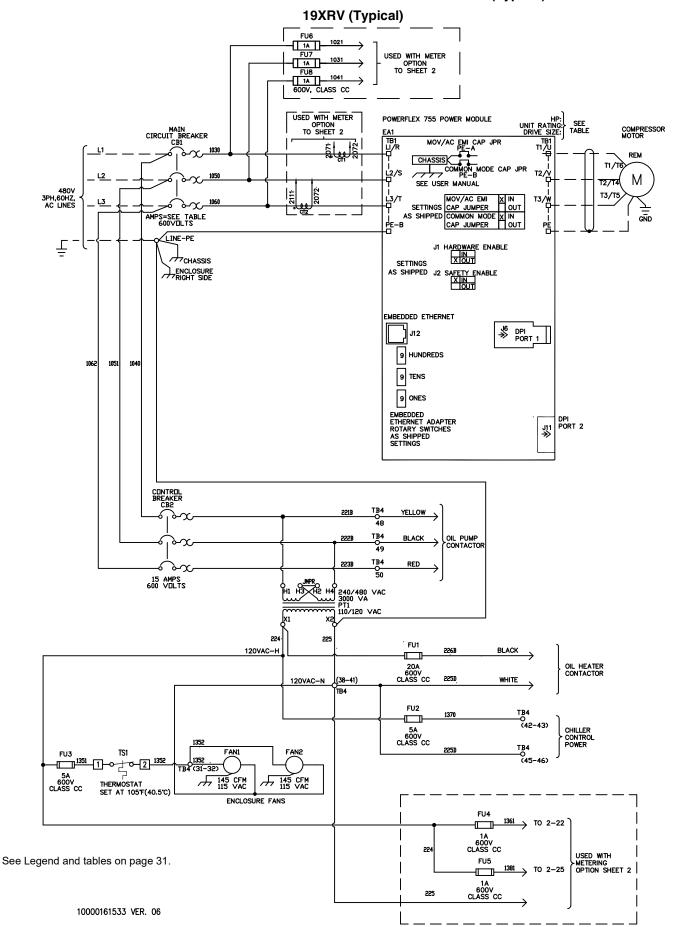
NOTES:

1. Liquid flow circuit: to install optional flow device, wire as shown (NO) and replace jumper with a 4.3k resistor.

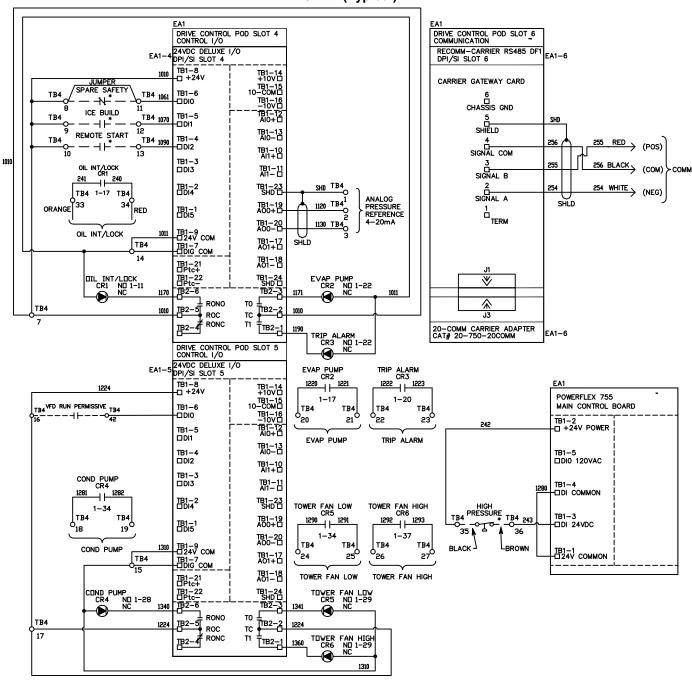
2. For TP compressor, the condenser flow switch must be installed in series with the cooler flow switch. Do not connect condenser flow switch to J3 (Lower) 23 and 24.

3. For TP compressor, remove 4.3k resistor between J3 (Lower) 20 and 21.

## APPENDIX A — WIRING SCHEMATICS (CONT) ROCKWELL POWERFLEX 755 WIRING SCHEMATIC (Typical)



## APPENDIX A — WIRING SCHEMATICS (CONT) ROCKWELL POWERFLEX 755 WIRING SCHEMATIC (Typical) 19XRV (Typical)

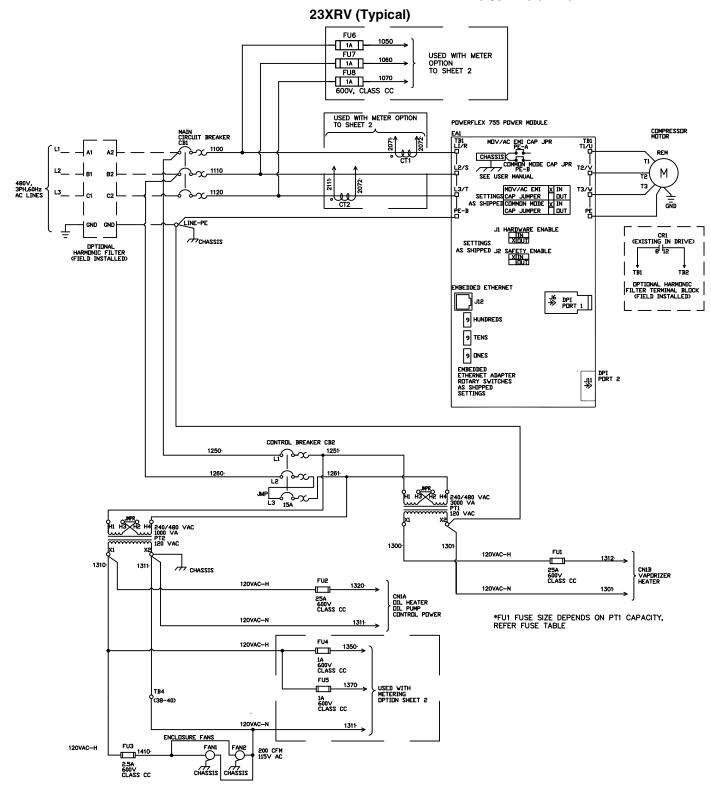


THIS EQUIPMENT CONFORMS TO CARRIER SPECIFICATION Z-417

See Legend and tables on page 31.

### **APPENDIX A — WIRING SCHEMATICS (CONT)**

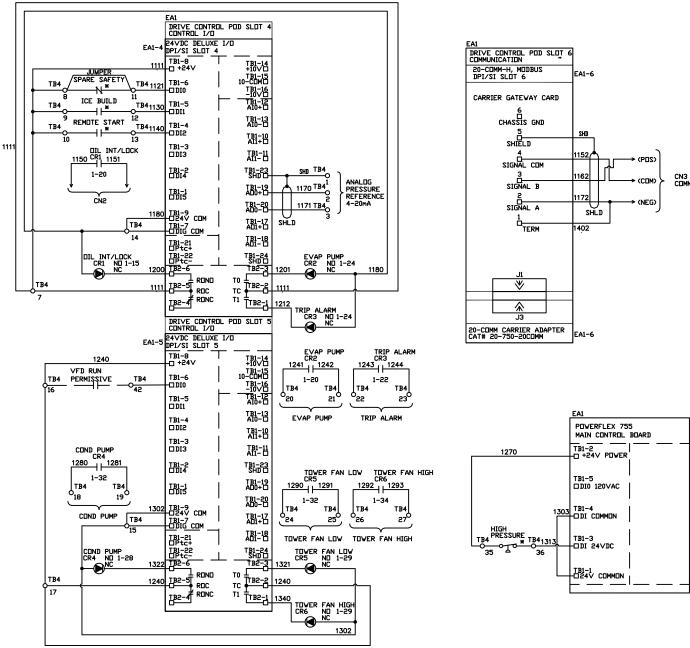
### **ROCKWELL POWERFLEX 755 WIRING SCHEMATIC (Typical) (cont)**



### APPENDIX A — WIRING SCHEMATICS (CONT)

### **ROCKWELL POWERFLEX 755 WIRING SCHEMATIC (Typical) (cont)**

### 23XRV Typical (cont)



See Legend and tables on page 31.

### APPENDIX A — WIRING SCHEMATICS (CONT) **ROCKWELL POWERFLEX 755 WIRING SCHEMATIC (Typical) (cont)**

**LEGEND** 

### **LEGEND AND TABLES FOR 19XRV**

### **LEGEND AND TABLES FOR 23XRV**

LEGEND

CAP CapacitorCircuit Breaker CB — Capacitor
CB — Circuit Breaker
COM — Common
COMM — Communication
COND — Condenser
CR — Control Relay
DPI/SI — Internal Communication Protocols Connections
EA — Electrical Assembly
EMI — Electro-Magnetic Interference
EVAP — Evaporator
FU — Fuse
GND — Ground
JMPR — Jumper
M — Motor
NC — Normally Closed
NO — Normally Open
PE — Potential Earth (Ground)
POD — I/O Card Mounting Board Slot
REM — Remote
RO — Relay Output

RO

 Relay Output
 Relay Output Common ROC

SHLD

Shield
Terminal Block TB

CAP CapacitorCircuit Breaker CB COM — Common CommunicationCondenserControl Relay COMM COND

CR DPI/SI

EA EMI

 Control Relay
 Internal Communication Protocols Connections
 Electrical Assembly
 Electro-Magnetic Interference
 Evaporator
 Fuse
 Ground
 Jumper
 Motor
 Normally Closed
 Normally Open
 Potential Earth (Ground)
 I/O Card Mounting Board Slot
 Remote
 Relay Output **EVAP** FU GND **JMPR** M NC

NO

PΕ POD

REM RO

 Relay Output
 Relay Output Common ROC

SHLD TB

ShieldTerminal Block

MAIN CIRCUIT BREAKER/DRIVE RATING TABLE	FOR 19XRV
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HP	UNIT RATING	MAIN CIRCUIT BREAKER CB1	FRAME SIZE
200	248A	400A	6
300	361A	600A	7
400	477A	600A	7

### MAIN CIRCUIT BREAKER/DRIVE RATING TABLE FOR 23XRV

HP	UNIT RATING	MAIN CIRCUIT BREAKER CB1	FRAME SIZE
300	361A	600A	7
400	477A	600A	7

FUSE TABLE FOR 19XRV			
REF	FUSE DESCRIPTION	LITTEL FUSE PART NUMBER	
FU1	CLASS CC, 20A 600V	CCMR020	
FU2	CLASS CC. 5A 600V	CCMR005	
FU3	02,100 00, 0,10001		
FU4			
FU5		CCMR001	
FU6	CLASS CC, 1A 600V		
FU7			
FU8			

FUSE TABLE FOR 23XRV		
REF	FUSE DESCRIPTION	LITTEL FUSE PART NUMBER
FU1	CLASS CC, 15/25A 600V	CCMR020
FU2	CLASS CC, 25A 600V	CCMR025
FU3	CLASS CC, 2.5A 600V	CCMR02.5
FU4		
FU5		
FU6	CLASS CC, 1A 600V	CCMR001
FU7		
FU8		

# APPENDIX A — WIRING SCHEMATICS (CONT) ROCKWELL POWERFLEX 755 WIRING SCHEMATIC (Typical) (cont) 19XRV,23XRV METER OPTION

